

Strong laws under trimming - a comparison between iid random variables and dynamical systems

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dynamical systems - pure and applied,
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- 1 The finite expectation case
- 2 The example $\mathbb{P}(X_1 > x) = L(x)/x$
- 3 The example $\mathbb{P}(X_1 > x) = L(x)/x^\alpha$, $\alpha \in (0, 1)$
 - The i.i.d. case
 - The dynamical systems case
 - Mean convergence

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Theorem 1.2 ([Feller, 1946, Chow and Robbins, 1961])

Let (X_n) be a sequence of i.i.d. random variables with $\mathbb{E}(X_1) < \infty$. Given any sequence of constants $(d_n)_{n \in \mathbb{N}}$ with $d_n > 0$ for all n , then

$$\limsup_{n \rightarrow \infty} \frac{S_n}{d_n} = \infty \text{ a.s. or } \liminf_{n \rightarrow \infty} \frac{S_n}{d_n} = 0 \text{ a.s.}$$

In the ergodic case we have analog statements:

Theorem 1.3 (Ergodic Theorem [Birkhoff, 1931])

Let $(\Omega, \mathcal{B}, \mu, T)$ be an ergodic, probability measure preserving dynamical system and let $f: \Omega \rightarrow \mathbb{R}$. If $(X_n) = (f \circ T^{n-1})$ and $\mathbb{E}(X_1) < \infty$, then

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Theorem 1.4 ([Aronson, 1977])

Let $(\Omega, \mathcal{B}, \mu, T)$ be an ergodic, probability measure preserving dynamical system and let $f: \Omega \rightarrow \mathbb{R}$. Further, let $(X_n) = (f \circ T^{n-1})$ and $\mathbb{E}(X_1) = \infty$. Given any sequence of constants $(d_n)_{n \in \mathbb{N}}$ with $d_n > 0$ for all n , then

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Definition 2.1

The sum $S_n^{b_n}$ is called

- *lightly trimmed sum* if $b_n = r \in \mathbb{N}$,
- *intermediately (moderately) trimmed sum* if $\lim_{n \rightarrow \infty} b_n = \infty$ and $b_n = o(n)$,
- *heavily trimmed sum* if $b_n \sim \kappa \cdot n$, $0 < \kappa < 1$.

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- If (X_n) are sufficiently fast ψ -mixing it follows from [Aaronson and Nakada, 2003, Application of Theorem 1.1] that

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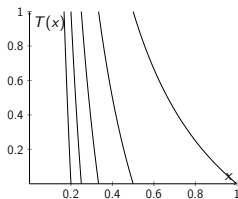
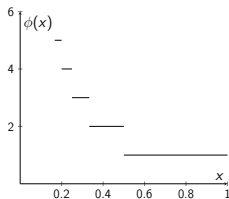
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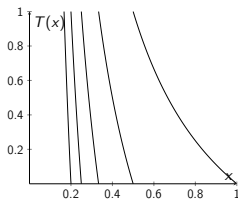
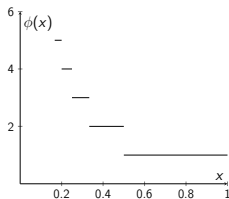
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Then $a_n(x) = \phi \circ \tau^{n-1}(x)$.

Lemma 2.2 ([Diamond and Vaaler, 1986])

If $X_n := a_n$, $n \in \mathbb{N}$, then we have that

$$\lim_{n \rightarrow \infty} \frac{S_n^1}{n \log n} = \frac{1}{\log 2} \text{ a.s.}$$

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However, ψ -mixing is a strong condition on dynamical systems and not all interesting dynamical systems are ψ -mixing...

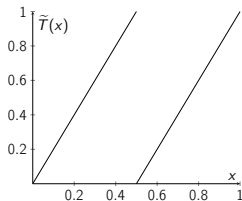
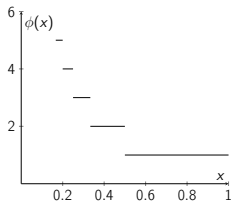
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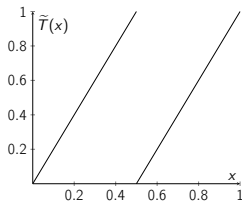
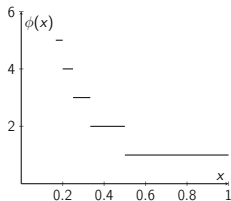
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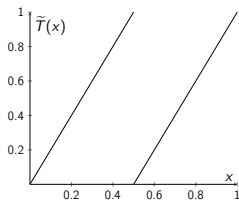
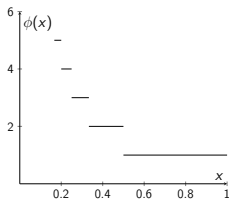
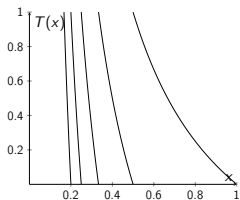
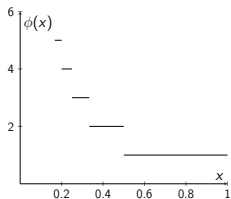


Theorem 2.3 ([Haynes, 2014, Theorem 4, generalized])

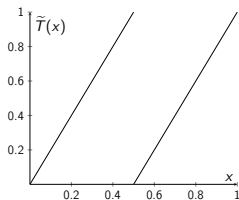
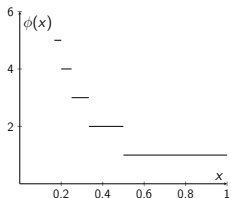
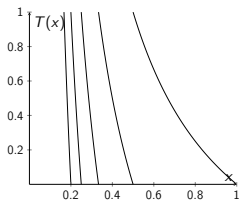
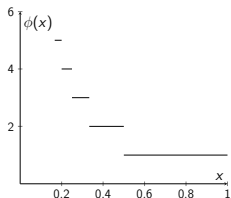
If $X_n = \phi \circ \tilde{T}^{n-1}$, then for all positive valued sequences $(d_n)_{n \in \mathbb{N}}$ and $k \in \mathbb{N}$ we have (with respect to the Lebesgue measure λ) that either

$$\limsup_{n \rightarrow \infty} \frac{S_n^k}{d_n} = \infty \text{ a.s. or } \liminf_{n \rightarrow \infty} \frac{S_n^k}{d_n} = 0 \text{ a.s.}$$

Comparison: Continued fractions (left) / doubling map (right)

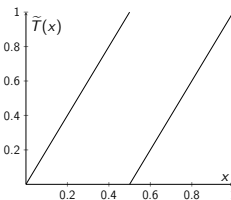
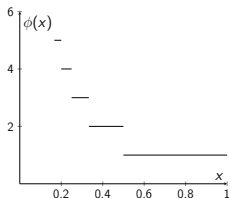
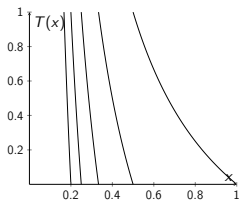
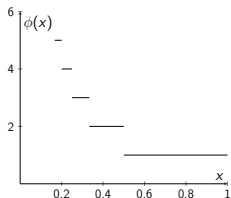


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Main difference: The observable ϕ obeys the structure of the underlying dynamics T but not of \tilde{T} .

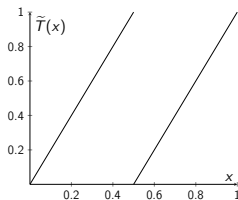
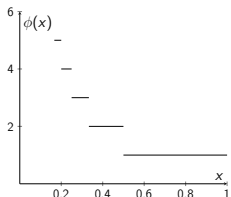
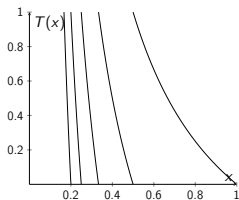
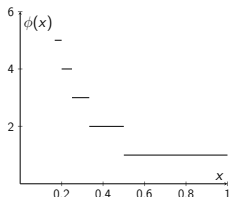
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So let's try intermediate trimming!

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Let $(X_n) = (\phi \circ \tilde{T}^{n-1})$ and let $\lim_{n \rightarrow \infty} b_n / \log^{1/4} n = 0$. If there exists $\psi \in \Psi$ such that

$$b_n := \left\lfloor \frac{\log \psi(\lfloor \log n \rfloor) - \log \log n}{\log 2} \right\rfloor,$$

then there exists a norming sequence (d_n) such that

$$\lim_{n \rightarrow \infty} \frac{S_n^{b_n}}{d_n} = 1 \text{ a.s.} \quad (1)$$

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It is work in progress to determine limit laws for more general settings than the doubling map and the observable ϕ .

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- But there are also distribution functions $F(x) = 1 - L(x)/x$ such that there is no strong law of large numbers under light trimming, one example is given in [Aaronson and Nakada, 2003].
- To my knowledge for such functions not more is known neither in the i.i.d. nor in the dynamical systems setting.

The example $\mathbb{P}(X_1 > x) = L(x)/x^\alpha$, $\alpha \in (0, 1)$

The i.i.d. case

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Theorem 3.1 ([Haeusler and Mason, 1987, Haeusler, 1993, Applications from])

Let (X_n) be a sequence of i.i.d. non-negative random variables such that $F(x) = 1 - L(x)/x^\alpha$ with L slowly varying and $\alpha \in (0, 1)$. Further, let $(b_n) = o(n)$ a sequence of natural numbers.

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If $\liminf_{n \rightarrow \infty} b_n / \log \log n = \infty$, then there exists a sequence (d_n) such that

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The norming sequence (d_n) can be given explicitly.

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The dynamical systems case

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Consider two new systems: Define

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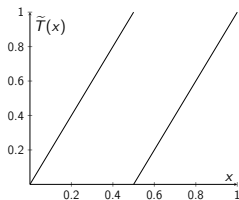
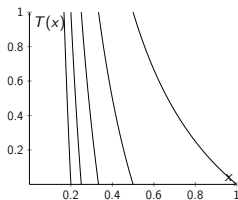
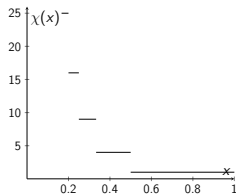
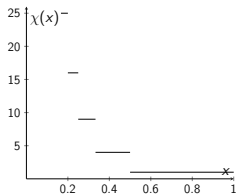
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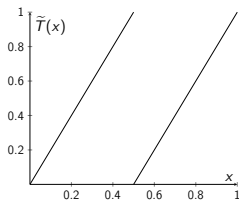
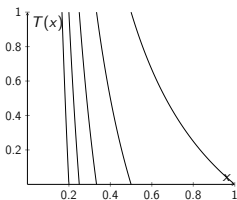
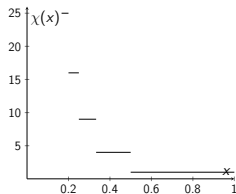
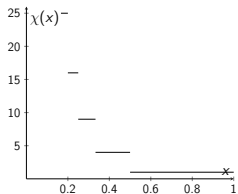
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$$\begin{aligned} \chi: [0, 1] &\rightarrow \mathbb{R}_{>0} & T: [0, 1] &\rightarrow [0, 1], & \tilde{T}: [0, 1] &\rightarrow [0, 1], \\ x &\mapsto [1/x]^2 & x &\mapsto 1/x \pmod{1} & x &\mapsto 2x \pmod{1}. \end{aligned}$$



For $(X_n) = (\chi \circ T^{n-1})$ and for $(X_n) = (\chi \circ \tilde{T}^{n-1})$ we obtain the same trimmed strong law:

Theorem 3.2 (Application of [Kesseböhmer and S., 2018, Theorem 1.7])

Let X_n be given as above. Further, let $(b_n)_{n \in \mathbb{N}}$ be a sequence of natural numbers tending to infinity with $b_n = o(n)$. If

$$\lim_{n \rightarrow \infty} \frac{b_n}{\log \log n} = \infty, \quad (3)$$

then there exists a positive valued sequence $(d_n)_{n \in \mathbb{N}}$ such that

$$\lim_{n \rightarrow \infty} \frac{S_n}{d_n} = 1 \text{ a.s.} \quad (4)$$

In this case $d_n \sim \frac{n^2}{b_n}$.

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We note that in both cases $(X_n) = (\chi \circ T^{n-1})$ and $(X_n) = (\chi \circ \tilde{T}^{n-1})$ the condition on the norming sequence (b_n) is the same as in the i.i.d. case.

- Indeed [Kesseböhmer and S., 2018] gives general conditions for dynamical systems fulfilling a spectral gap property on the transfer operator and observables with regularly varying tails with exponent strictly between 0 and 1 for a strong law under intermediate trimming to hold.

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- As an application we obtain strong laws under trimming for piecewise expanding interval maps.
- Another application of these results gives strong laws under trimming for subshifts of finite type, see [Kesseböhmer and S., 2019a].

The example $\mathbb{P}(X_1 > x) = L(x)/x^\alpha$, $\alpha \in (0, 1)$

Mean convergence

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- The strong law of large numbers or Birkhoff's ergodic theorem give for i.i.d. or ergodic and identically distributed, integrable random variables

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- In the generalized case for non-integrable random variables we obtain a strong law after trimming, i.e. there exists a (possibly constant) sequence of natural numbers (b_n) and a norming sequence (d_n) fulfilling

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- Can we say anything about the norming sequence (d_n) ?
- In general: No!

Even for i.i.d. random variables there are examples for which (5) holds but $\mathbb{E}(S_n^{b_n}) = \infty$, see [Kesseböhmer and S., 2019c, Remark 3].

The example $\mathbb{P}(\chi_1 > x) = L(x)/x^\alpha$, $\alpha \in (0, 1)$

Mean convergence

However, remember the two systems from before:

$$\chi: [0, 1] \rightarrow \mathbb{R}_{>0}$$

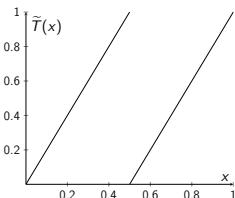
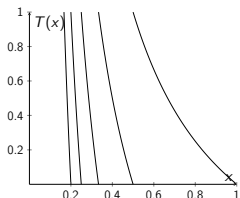
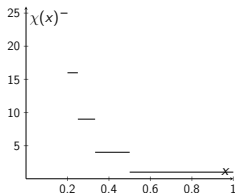
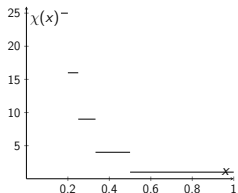
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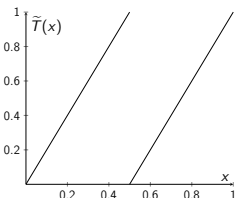
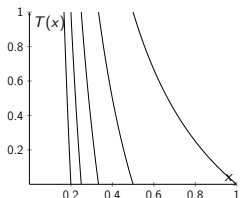
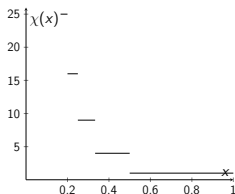
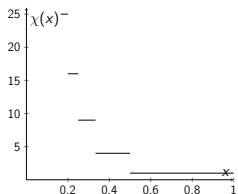
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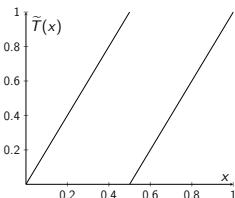
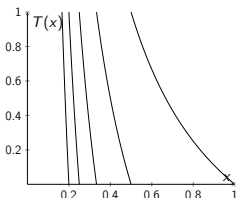
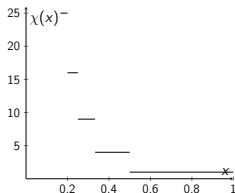
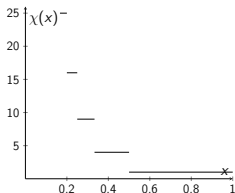
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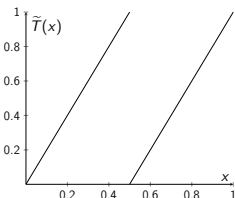
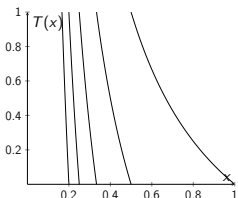
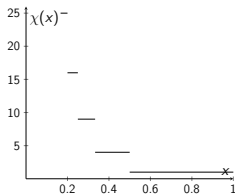
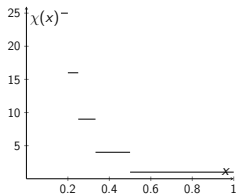
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For details see [Kesseböhmer and S., 2019b].

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- As seen before the ψ -mixing property is essential.



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